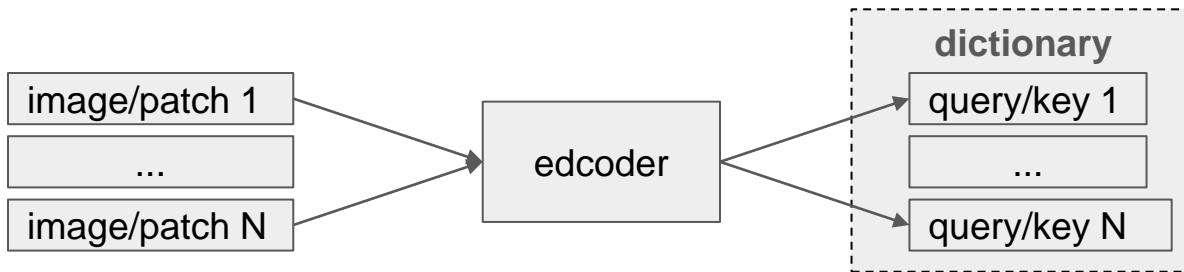


Momentum Contrast for Unsupervised Visual Representation Learning

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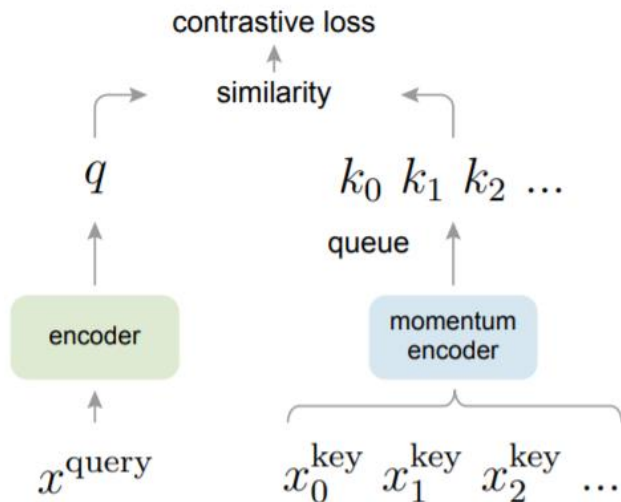
Background

- Unsupervised representation learning
 - highly **successful** in natural language processing
 - generally **lag behind** in computer vision
- Approaches related to the **contrastive loss** show promising results.
 - Build dynamic **dictionaries**
 - Trains **encoders** to perform dictionary look-up
 - An encoded “**query**” (images or patches) should be **similar** to its matching key and **dissimilar** to others

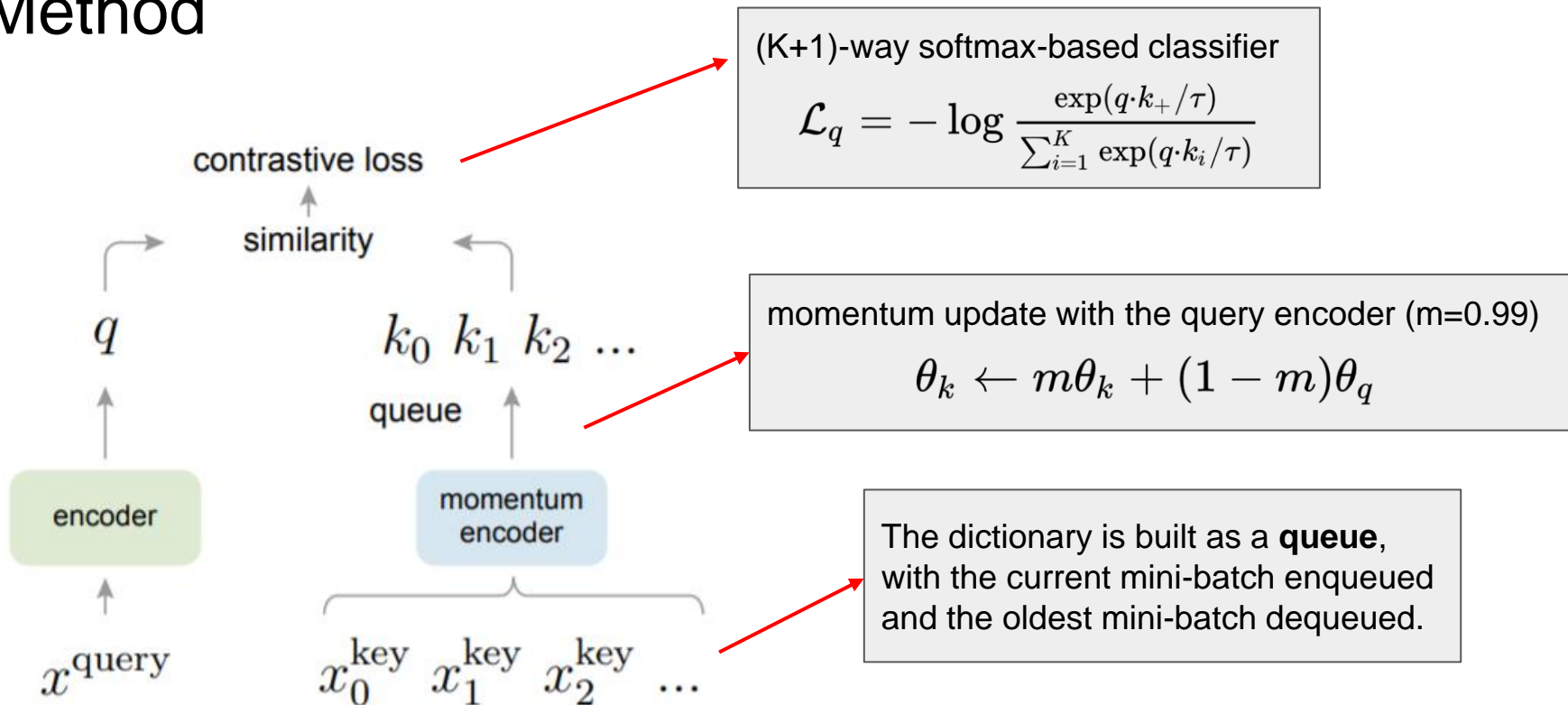


Method

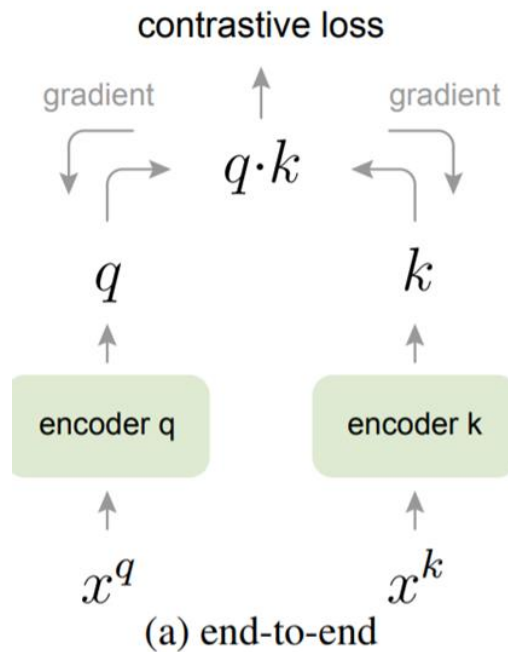
- Hypothesize: the dictionary should be **large** and **consistent**
- This paper presents **Momentum Contrast (MoCo)** as a way of building **large and consistent dictionaries** for unsupervised learning with a contrastive loss



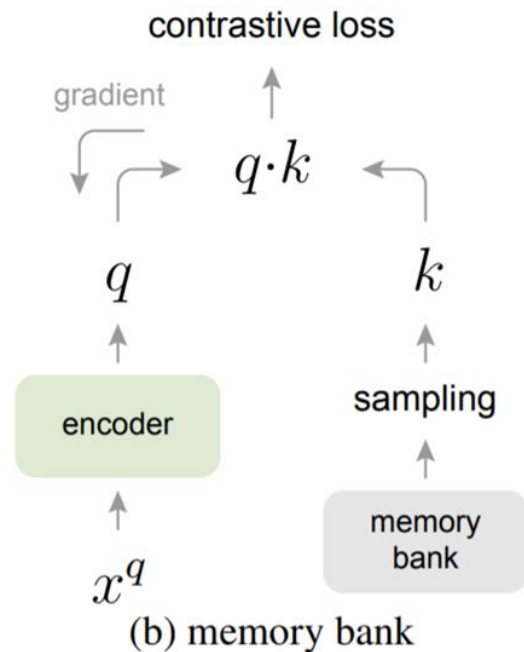
Method



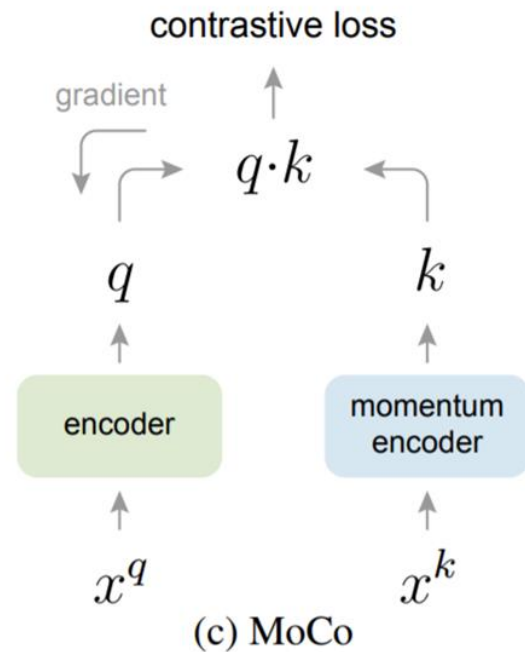
Relations to previous mechanisms



Encoder q and k are **different**.



The representation of a sample in memory bank is **updated when it was last seen**.



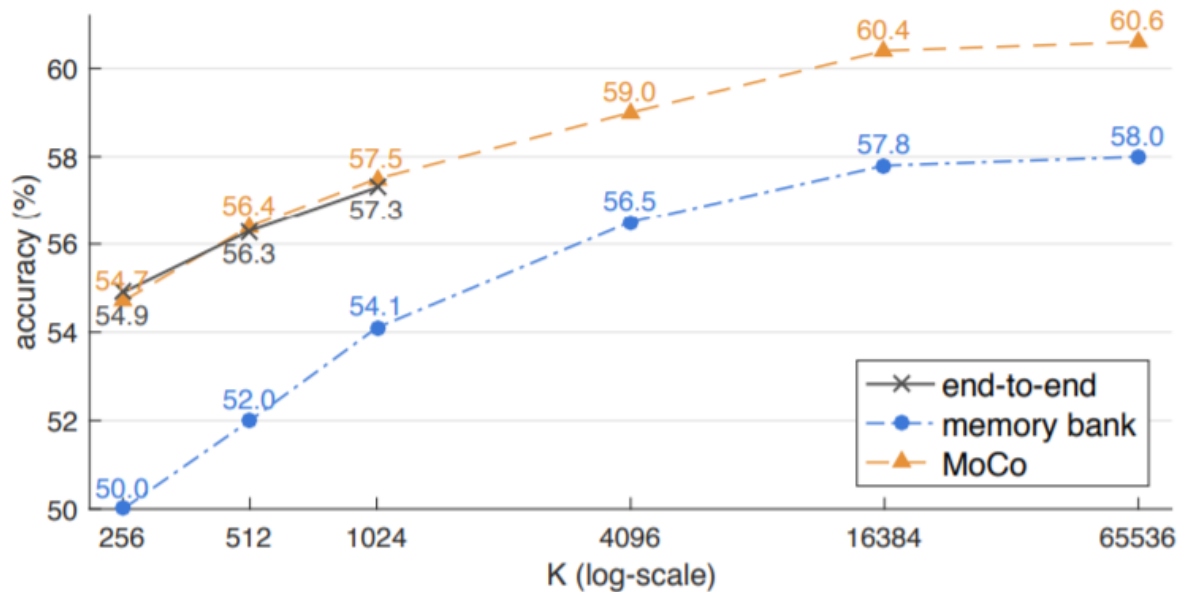
compare with (a) \rightarrow consistent
compare with (b) \rightarrow large

Experiment

- Answer two-fold questions
 - comparison of three mechanisms
 - performance of downstream tasks
- Dataset
 - **ImageNet-1M (IN-1M)**: ~1.28 million images in 1000 classes
 - **Instagram-1B (IG-1B)**: ~1 billion (940M) public images from ~1500 hashtags (long-tailed, unbalanced distribution)

Compare three mechanisms

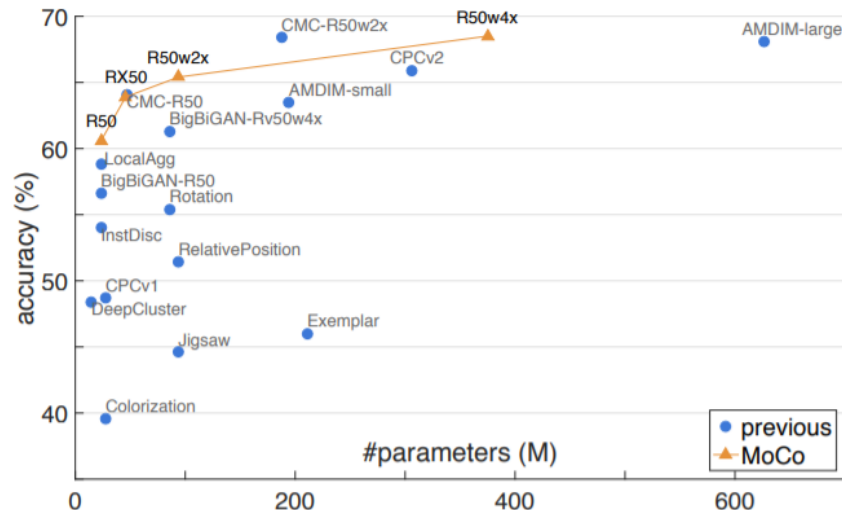
- linear classification on frozen features



K number of negative samples

Compare with previous methods

method	architecture	#params (M)	accuracy (%)
Exemplar [17]	R50w3×	211	46.0 [38]
RelativePosition [13]	R50w2×	94	51.4 [38]
Jigsaw [45]	R50w2×	94	44.6 [38]
Rotation [19]	Rv50w4×	86	55.4 [38]
Colorization [64]	R101*	28	39.6 [14]
DeepCluster [3]	VGG [53]	15	48.4 [4]
BigBiGAN [16]	R50	24	56.6
	Rv50w4×	86	61.3
<i>methods based on contrastive learning follow:</i>			
InstDisc [61]	R50	24	54.0
LocalAgg [66]	R50	24	58.8
CPC v1 [46]	R101*	28	48.7
CPC v2 [35]	R170* _{wider}	303	65.9
CMC [56]	R50 _{L+ab}	47	64.1 [†]
	R50w2× _{L+ab}	188	68.4 [†]
AMDIM [2]	AMDIM _{small}	194	63.5 [†]
	AMDIM _{large}	626	68.1 [†]
MoCo	R50	24	60.6
	RX50	46	63.9
	R50w2×	94	65.4
	R50w4×	375	68.6



Key observations:

- higher accuracy with less #parameters
- efficiency, less #parameters with higher accuracy

performance of downstream tasks

pre-train	AP ₅₀					AP	AP ₇₅	
	RelPos, by [14]	Multi-task [14]	Jigsaw, by [26]	LocalAgg [66]	MoCo	MoCo	Multi-task [14]	MoCo
super. IN-1M	74.2	74.2	70.5	74.6	74.4	42.4	44.3	42.7
unsup. IN-1M	66.8 (-7.4)	70.5 (-3.7)	61.4 (-9.1)	69.1 (-5.5)	74.9 (+0.5)	46.6 (+4.2)	43.9 (-0.4)	50.1 (+7.4)
unsup. IN-14M	-	-	69.2 (-1.3)	-	75.2 (+0.8)	46.9 (+4.5)	-	50.2 (+7.5)
unsup. YFCC-100M	-	-	66.6 (-3.9)	-	74.7 (+0.3)	45.9 (+3.5)	-	49.0 (+6.3)
unsup. IG-1B	-	-	-	-	75.6 (+1.2)	47.6 (+5.2)	-	51.7 (+9.0)

Table 4. Comparison with previous methods on object detection fine-tuned on PASCAL VOC trainval2007. Evaluation is on

pre-train	AP ₅₀	AP	AP ₇₅
random init.	64.4	37.9	38.6
super. IN-1M	81.4	54.0	59.1
MoCo IN-1M	81.1 (-0.3)	54.6 (+0.6)	59.9 (+0.8)
MoCo IG-1B	81.6 (+0.2)	55.5 (+1.5)	61.2 (+2.1)

(a) Faster R-CNN, R50-dilated-C5

pre-train	AP ₅₀	AP	AP ₇₅
random init.	60.2	33.8	33.1
super. IN-1M	81.3	53.5	58.8
MoCo IN-1M	81.5 (+0.2)	55.9 (+2.4)	62.6 (+3.8)
MoCo IG-1B	82.2 (+0.9)	57.2 (+3.7)	63.7 (+4.9)

(b) Faster R-CNN, R50-C4

Table 2. Object detection fine-tuned on PASCAL VOC

performance of downstream tasks

pre-train	COCO keypoint detection		
	AP^{kp}	AP_{50}^{kp}	AP_{75}^{kp}
random init.	65.9	86.5	71.7
super. IN-1M	65.8	86.9	71.9
MoCo IN-1M	66.8 (+1.0)	87.4 (+0.5)	72.5 (+0.6)
MoCo IG-1B	66.9 (+1.1)	87.8 (+0.9)	73.0 (+1.1)

pre-train	COCO dense pose estimation		
	AP^{dp}	AP_{50}^{dp}	AP_{75}^{dp}
random init.	39.4	78.5	35.1
super. IN-1M	48.3	85.6	50.6
MoCo IN-1M	50.1 (+1.8)	86.8 (+1.2)	53.9 (+3.3)
MoCo IG-1B	50.6 (+2.3)	87.0 (+1.4)	54.3 (+3.7)

pre-train	LVIS v0.5 instance segmentation		
	AP^{mk}	AP_{50}^{mk}	AP_{75}^{mk}
random init.	22.5	34.8	23.8
super. IN-1M [†]	24.4	37.8	25.8
MoCo IN-1M	24.1 (-0.3)	37.4 (-0.4)	25.5 (-0.3)
MoCo IG-1B	24.9 (+0.5)	38.2 (+0.4)	26.4 (+0.6)

pre-train	Cityscapes instance seg.		Semantic seg. (mIoU)	
	AP^{mk}	AP_{50}^{mk}	Cityscapes	VOC
random init.	25.4	51.1	65.3	39.5
super. IN-1M	32.9	59.6	74.6	74.4
MoCo IN-1M	32.3 (-0.6)	59.3 (-0.3)	75.3 (+0.7)	72.5 (-1.9)
MoCo IG-1B	32.9 (0.0)	60.3 (+0.7)	75.5 (+0.9)	73.6 (-0.8)

Further reading

- **A Simple Framework for Contrastive Learning of Visual Representations**
 - *Ting Chen, Simon Kornblith, Mohammad Norouzi, Geoffrey Hinton (Google Brain)*
- **Learning deep representations by mutual information estimation and maximization**
 - *R Devon Hjelm, Alex Fedorov, Samuel Lavoie-Marchildon, Karan Grewal, Adam Trischler, and Yoshua Bengio (ICLR 2019)*
- **Unsupervised feature learning via non-parametric instance discrimination**
 - *Zhirong Wu, Yuanjun Xiong, Stella Yu, and Dahua Lin (CVPR 2018 spotlight)*